

# ME 233 Advanced Control II

## Lecture 19

### Least Squares Parameter Estimation

# Least Squares Estimation

## Model

$$y(k) = \sum_{i=1}^n \phi_i(k-1) \theta_i$$

Where

- $y(k)$  observed output
- $\phi_i(k)$  **known** and measurable function
- $\theta_i$  **unknown** but constant parameter

# Least Squares Estimation

## Model

$$y(k) = \phi^T(k-1) \theta$$

Where

$y(k)$  measured output

$$\phi(k) = \underbrace{\begin{bmatrix} \phi_1(k) \\ \vdots \\ \phi_n(k) \end{bmatrix}}_{n \times 1 \text{ regressor}}$$

$$\theta = \underbrace{\begin{bmatrix} \theta_1 \\ \vdots \\ \theta_n \end{bmatrix}}_{\text{unknown vector}}$$

# Batch Least Squares Estimation


Assume that we have collected  $k$  data sets:

$$\left. \begin{array}{l} y(1), \dots, y(k) \\ \phi(0), \dots, \phi(k-1) \end{array} \right\} \text{collected data}$$

We want to find the parameter estimate at instant  $k$ :  $\hat{\theta}(k)$

that best fits **all collected** data in the **least squares** sense:

$$\min_{\hat{\theta}(k)} \left\{ \frac{1}{2} \sum_{j=1}^k \left[ y(j) - \phi^T(j-1) \hat{\theta}(k) \right]^2 \right\}$$

*kept constant in the summation* 

# Batch Least Squares Estimation

Defining the cost functional

$$V(\hat{\theta}(k)) = \frac{1}{2} \sum_{j=1}^k \left[ y(j) - \phi^T(j-1) \hat{\theta}(k) \right]^2$$

$\hat{\theta}(k)$  is obtained by solving

$$\frac{dV(\hat{\theta}(k))}{d\hat{\theta}(k)} = 0$$

# Batch Least Squares Solution

The least squares parameter estimate  $\hat{\theta}(k)$  which solves

$$\frac{dV(\hat{\theta}(k))}{d\hat{\theta}(k)} = 0$$

Satisfies the **normal equation**:

$$\underbrace{\left[ \sum_{i=1}^k \phi(i-1)\phi^T(i-1) \right]}_{n \times n \text{ matrix}} \hat{\theta}(k) = \underbrace{\sum_{i=1}^k \phi(i-1)y(i)}_{n \times 1 \text{ vector}}$$

# Normal Equation Derivation

$$\begin{aligned}
 V(\hat{\theta}(k)) &= \frac{1}{2} \sum_{j=1}^k \left[ y(j) - \phi^T(j-1) \hat{\theta}(k) \right]^2 \\
 &= \frac{1}{2} \left\| \begin{bmatrix} y(1) - \phi^T(0) \hat{\theta}(k) \\ \vdots \\ y(k) - \phi^T(k-1) \hat{\theta}(k) \end{bmatrix} \right\|^2 \\
 &= \frac{1}{2} \left\| \underbrace{\begin{bmatrix} y(1) \\ \vdots \\ y(k) \end{bmatrix}}_{Y(k)} - \underbrace{\begin{bmatrix} \phi^T(0) \\ \vdots \\ \phi^T(k-1) \end{bmatrix}}_{\Phi^T(k-1)} \hat{\theta}(k) \right\|^2
 \end{aligned}$$

# Normal Equation Derivation

$$\begin{aligned}
 V(\hat{\theta}(k)) &= \frac{1}{2} \left\| Y(k) - \Phi^T(k-1)\hat{\theta}(k) \right\|^2 \\
 &= \frac{1}{2} \left[ Y^T(k)Y(k) + \hat{\theta}^T(k)\Phi(k-1)\Phi^T(k-1)\hat{\theta}(k) \right. \\
 &\quad \left. - 2\hat{\theta}^T(k)\Phi(k-1)Y(k) \right]
 \end{aligned}$$

Taking the partial derivative with respect to  $\hat{\theta}(k)$

$$\frac{\partial V(\hat{\theta}(k))}{\partial \hat{\theta}(k)} = \Phi(k-1)\Phi^T(k-1)\hat{\theta}(k) - \Phi(k-1)Y(k)$$

For optimality, we therefore need

$$\Phi(k-1)\Phi^T(k-1)\hat{\theta}(k) = \Phi(k-1)Y(k)$$



# Normal Equation Derivation

$$\Phi(k-1) = [\phi(0) \ \cdots \ \phi(k-1)]$$

$$Y(k) = [y(1) \ \cdots \ y(k)]^T$$

For optimality, we need

$$\underbrace{\Phi(k-1)\Phi^T(k-1)}_{\sum_{i=1}^k \phi(i-1)\phi^T(i-1)} \hat{\theta}(k) = \underbrace{\Phi(k-1)Y(k)}_{\sum_{i=1}^k \phi(i-1)y(i)}$$

Therefore, we need

$$\left[ \sum_{i=1}^k \phi(i-1)\phi^T(i-1) \right] \hat{\theta}(k) = \sum_{i=1}^k \phi(i-1)y(i)$$



# Batch Least Squares Estimation

The solution of the normal equation

$$\left[ \sum_{i=1}^k \phi(i-1)\phi^T(i-1) \right] \hat{\theta}(k) = \sum_{i=1}^k \phi(i-1)y(i)$$

Is given by:

$$\hat{\theta}(k) = \left[ \sum_{i=1}^k \phi(i-1)\phi^T(i-1) \right]^{\#} \sum_{i=1}^k \phi(i-1)y(i)$$

*Pseudoinverse*

# Moore-Penrose pseudoinverse

- Let  $A$  have the singular value decomposition

$$A = \begin{matrix} \text{orthogonal matrices} \\ \swarrow \quad \searrow \\ \begin{bmatrix} U_1 & U_2 \end{bmatrix} \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} V_1^T \\ V_2^T \end{bmatrix} \end{matrix}$$

$$\Sigma = \text{diag}(\sigma_1, \dots, \sigma_r) \quad \sigma_1 \geq \dots \geq \sigma_r > 0$$

- Then the Moore-Penrose pseudoinverse of  $A$  is

$$A^\# = \begin{bmatrix} V_1 & V_2 \end{bmatrix} \begin{bmatrix} \Sigma^{-1} & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} U_1^T \\ U_2^T \end{bmatrix}$$

In MATLAB: `pinv(A)`

# Moore-Penrose pseudoinverse

Let  $A \in \mathcal{R}^{n \times m}$  and  $A^\#$  be its Moore-Penrose pseudoinverse

Then  $A^\#$  has the dimension of  $A^T$  and satisfies:

- $A A^\# A = A$
- $A^\# A A^\# = A^\#$
- $A^\# A$  and  $A A^\#$  are Hermitian

In this case, since  $A = \Phi \Phi^T$

$$\Phi = \begin{bmatrix} \phi(0) \cdots \phi(k-1) \end{bmatrix}$$

$$A A^\# \Phi = \Phi$$

# Batch Least Squares Estimation

Assume that we have collected sufficient data and the data has sufficient richness so that

$$\left[ \sum_{i=1}^k \phi(i-1)\phi^T(i-1) \right] = \phi(0)\phi^T(0) + \phi(1)\phi^T(1) + \dots + \phi(k-1)\phi^T(k-1)$$

has full rank.

Then,

$$\hat{\theta}(k) = \underbrace{\left[ \sum_{i=1}^k \phi(i-1)\phi^T(i-1) \right]^{-1}}_{F(k)} \sum_{i=1}^k \phi(i-1) y(i)$$

# Recursive Least Squares (RLS)

Assume that we have collected  $k-1$  sets of data and have computed  $\hat{\theta}(k-1)$  using

$$\hat{\theta}(k-1) = \underbrace{\left[ \sum_{i=1}^{k-1} \phi(i-1)\phi^T(i-1) \right]^{-1}}_{F(k-1)} \sum_{i=1}^{k-1} \phi(i-1)y(i)$$

Then, given a new set of data:  $y(k)$   $\phi(k-1)$

We want to find  $\hat{\theta}(k)$  in a recursive fashion:

$$\hat{\theta}(k) = \hat{\theta}(k-1) + [\textit{correction term}]$$

# Recursive Least Squares Algorithm

Define the ***a-priori*** output estimate:

$$\hat{y}^o(k) = \phi^T(k-1)\hat{\theta}(k-1)$$

and the ***a-priori*** output estimation error:

$$e^o(k) = y(k) - \phi^T(k-1)\hat{\theta}(k-1)$$

The RLS algorithm is given by:

$$\hat{\theta}(k) = \hat{\theta}(k-1) + F(k)\phi(k-1)e^o(k)$$

where  $F(k)$  has the recursive relationship on the next slide

# Recursive Least Squares Gain

The RLS gain  $F(k)$  is defined by

$$F^{-1}(k) = \sum_{i=1}^k \phi(i-1)\phi^T(i-1)$$

Therefore,

$$F^{-1}(k) = F^{-1}(k-1) + \phi(k-1)\phi^T(k-1)$$

Using the matrix inversion lemma, we obtain

$$F(k) = F(k-1) - \frac{F(k-1)\phi(k-1)\phi(k-1)^T F(k-1)}{1 + \phi(k-1)^T F(k-1)\phi(k-1)}$$



# Recursive Least Squares Derivation

Define the least squares gain matrix  $F(k)$

$$F(k) = \left[ \sum_{i=1}^k \phi(i-1)\phi^T(i-1) \right]^{-1}$$

Therefore,

$$\hat{\theta}(k) = F(k) \sum_{i=1}^k \phi(i-1)y(i)$$

# Recursive Least Squares Derivation

Notice that

$$\begin{aligned}\hat{\theta}(k) &= F(k) \sum_{i=1}^k \phi(i-1)y(i) \\ &= F(k) \left[ \phi(k-1)y(k) + \underbrace{\sum_{i=1}^{k-1} \phi(i-1)y(i)}_{F^{-1}(k-1)\hat{\theta}(k-1)} \right]\end{aligned}$$

$$F^{-1}(k-1) = F^{-1}(k) - \phi(k-1)\phi^T(k-1)$$

# Recursive Least Squares Derivation

Therefore plugging the previous two results,

$$\begin{aligned}\hat{\theta}(k) &= F(k) \left[ \left( F(k)^{-1} - \phi(k-1) \phi^T(k-1) \right) \hat{\theta}(k-1) \right. \\ &\quad \left. + \phi(k-1) y(k) \right]\end{aligned}$$

And rearranging terms, we obtain

$$\begin{aligned}\hat{\theta}(k) &= \hat{\theta}(k-1) \\ &\quad + F(k) \phi(k-1) \underbrace{\left[ y(k) - \phi^T(k-1) \hat{\theta}(k-1) \right]}_{e^o(k)}\end{aligned}$$



# Recursive Least Squares Estimation

Define the ***a-priori*** output estimate:

$$\hat{y}^o(k) = \phi^T(k-1)\hat{\theta}(k-1)$$

and the ***a-priori*** output estimation error:

$$e^o(k) = y(k) - \phi^T(k-1)\hat{\theta}(k-1)$$

The RLS algorithm is given by:

$$\hat{\theta}(k) = \hat{\theta}(k-1) + F(k)\phi(k-1)e^o(k)$$

# Recursive Least Squares Estimation

**Recursive computation of  $F(k)$**

$$F^{-1}(k) = \sum_{i=1}^k \phi(i-1)\phi^T(i-1)$$

Therefore,

$$F^{-1}(k) = F^{-1}(k-1) + \phi(k-1)\phi^T(k-1)$$

Using the matrix inversion lemma, we obtain

$$F(k) = F(k-1) - \frac{F(k-1)\phi(k-1)\phi(k-1)^T F(k-1)}{1 + \phi(k-1)^T F(k-1)\phi(k-1)}$$

# Recursive Least Squares Estimation

## Matrix inversion lemma:

$$F^{-1}(k) = F^{-1}(k-1) + \phi(k-1)\phi^T(k-1)$$

- Multiply by  $F(k-1)$  on the right and  $F(k)$  on the left:

$$F(k-1) = F(k) + F(k)\phi(k-1)\phi(k-1)^T F(k-1)$$

- Multiply by  $\phi(k-1)$  on the right:

$$F(k-1)\phi(k-1) = F(k)\phi(k-1) + F(k)\phi(k-1) \underbrace{\phi(k-1)^T F(k-1)\phi(k-1)}_{\text{scalar}}$$

# Recursive Least Squares Estimation

## Matrix inversion lemma:

- Rearranging terms,

$$F(k-1)\phi(k-1) = \left[1 + \phi(k-1)^T F(k-1)\phi(k-1)\right] F(k)\phi(k-1)$$

- Solving for  $F(k)\phi(k-1)$

$$F(k)\phi(k-1) = \frac{F(k-1)\phi(k-1)}{\left[1 + \phi(k-1)^T F(k-1)\phi(k-1)\right]}$$

# Recursive Least Squares Estimation

## Matrix inversion lemma:

- Plug

$$F(k)\phi(k-1) = \frac{F(k-1)\phi(k-1)}{\left[1 + \phi(k-1)^T F(k-1)\phi(k-1)\right]}$$

into

$$F(k) = F(k-1) - \underbrace{F(k)\phi(k-1)} \phi(k-1)^T F(k-1)$$

to obtain

$$F(k) = F(k-1) - \frac{F(k-1)\phi(k-1)\phi(k-1)^T F(k-1)}{1 + \phi(k-1)^T F(k-1)\phi(k-1)}$$



# RLS Estimation Algorithm

**A-priori version:**

$$e^o(k+1) = y(k+1) - \phi^T(k)\hat{\theta}(k)$$

$$\hat{\theta}(k+1) = \hat{\theta}(k) + F(k+1)\phi(k)e^o(k+1)$$

$$F(k+1) = F(k) - \frac{F(k)\phi(k)\phi^T(k)F(k)}{1 + \phi^T(k)F(k)\phi(k)}$$

Initial conditions:

$$F(0) = F^T(0) > 0 \quad \hat{\theta}(0)$$

# RLS Estimation Algorithm

**A-posteriori version (used to prove that  $e(k) \rightarrow 0$ ):**

$$e^o(k+1) = y(k+1) - \phi^T(k)\hat{\theta}(k)$$

$$e(k+1) = \frac{e^o(k+1)}{1 + \phi^T(k)F(k)\phi(k)}$$

$$\hat{\theta}(k+1) = \hat{\theta}(k) + F(k)\phi(k)e(k+1)$$

$$F(k+1) = F(k) - \frac{F(k)\phi(k)\phi^T(k)F(k)}{1 + \phi^T(k)F(k)\phi(k)}$$

# RLS Estimation Algorithm

Define the parameter estimation error:

$$\tilde{\theta}(k) = \theta - \hat{\theta}(k)$$

Notice that, since

$$y(k) = \phi^T(k-1)\theta$$

And the a-priori error is

$$e^o(k) = y(k) - \phi^T(k-1)\hat{\theta}(k-1)$$

We obtain,

$$\begin{aligned} e^o(k) &= \phi^T(k-1)\theta - \phi^T(k-1)\hat{\theta}(k-1) \\ &= \phi^T(k-1) \underbrace{[\theta - \hat{\theta}(k-1)]}_{\tilde{\theta}(k-1)} \end{aligned}$$

# RLS Estimation Algorithm

Thus, the a-priori output estimation error can be written as

$$e^o(k) = \phi^T(k-1)\tilde{\theta}(k-1)$$

Similarly, define the **a-posteriori output and estimation error** :

$$\hat{y}(k) = \phi^T(k-1)\hat{\theta}(k)$$

$$e(k) = y(k) - \hat{y}(k)$$

then,

$$e(k) = \phi^T(k-1)\tilde{\theta}(k)$$

# RLS Estimation Algorithm

**Derivation of the RLS A-posteriori version:**

$$\hat{\theta}(k) = \hat{\theta}(k-1) + F(k)\phi(k-1)e^o(k)$$

$$e^o(k) = y(k) - \phi^T(k-1)\hat{\theta}(k-1)$$

Remember that,

$$F(k)\phi(k-1) = \frac{F(k-1)\phi(k-1)}{\left[1 + \phi(k-1)^T F(k-1)\phi(k-1)\right]}$$

Thus,

$$\hat{\theta}(k+1) = \hat{\theta}(k) + \frac{F(k)\phi(k)}{1 + \phi^T(k)F(k)\phi(k)} e^o(k+1)$$

# RLS Estimation Algorithm

Multiplying by  $\phi^T(k)$  to the left of

$$\tilde{\theta}(k+1) = \tilde{\theta}(k) - \frac{F(k)\phi(k)}{1 + \phi^T(k)F(k)\phi(k)} e^o(k+1)$$

to obtain,

$$\underbrace{\phi^T(k)\tilde{\theta}(k+1)}_{e(k+1)} = \underbrace{\phi^T(k)\tilde{\theta}(k)}_{e^o(k+1)} - \frac{\phi^T(k)F(k)\phi(k)}{1 + \phi^T(k)F(k)\phi(k)} e^o(k+1)$$

Thus,

$$\begin{aligned} e(k+1) &= e^o(k+1) - \frac{\phi^T(k)F(k)\phi(k)}{1 + \phi^T(k)F(k)\phi(k)} e^o(k+1) \\ &= \frac{e^o(k+1)}{1 + \phi^T(k)F(k)\phi(k)} \end{aligned}$$

# RLS Estimation Algorithm

Therefore, from

$$\hat{\theta}(k+1) = \hat{\theta}(k) + F(k)\phi(k) \frac{e^o(k+1)}{1 + \phi^T(k)F(k)\phi(k)}$$

We obtain,

$$\hat{\theta}(k+1) = \hat{\theta}(k) + F(k)\phi(k) e(k+1)$$

$$e(k+1) = \frac{e^o(k+1)}{1 + \phi^T(k)F(k)\phi(k)}$$

# RLS with forgetting factor

The inverse of the gain matrix in the RLS algorithm is given by:

$$F^{-1}(k) = F^{-1}(k-1) + \phi(k-1)\phi^T(k-1)$$

Its trace is given by:

$$\text{tr} [F^{-1}(k)] = \text{tr} [F^{-1}(k-1)] + \|\phi(k-1)\|^2$$

which always increases when  $\|\phi(k-1)\| \neq 0$



# RLS with forgetting factor

Similarly, the trace of the gain matrix is given by

$$\text{tr}[F(k)] = \text{tr}[F(k-1)] - \frac{\|F(k-1)\phi(k-1)\|^2}{1 + \phi^T(k-1)F(k-1)\phi(k-1)}$$

always decreases when  $\|F(k-1)\phi(k-1)\| \neq 0$

Problem: RLS eventually stops updating

# RLS with forgetting factor

We can modify cost function to “forget” old data

$$V(\hat{\theta}(k)) = \frac{1}{2} \sum_{j=1}^k \lambda^{(k-j)} \left[ y(j) - \phi^T(j-1) \hat{\theta}(k) \right]^2$$

$$0 < \lambda \leq 1$$

Key idea: Discount old data, e.g. the term

$$\lambda^{(k-1)} \left[ y(1) - \phi^T(0) \hat{\theta}(k) \right]^2$$

is small when  $k$  is large since  $\lim_{m \rightarrow \infty} \lambda^m = 0$

# RLS with forgetting factor

**A-priori version:**

$$\left. \begin{aligned}
 e^o(k+1) &= y(k+1) - \phi^T(k)\hat{\theta}(k) \\
 \hat{\theta}(k+1) &= \hat{\theta}(k) + F(k+1)\phi(k)e^o(k+1)
 \end{aligned} \right\} \begin{array}{l} \text{Same as RLS} \\ \text{without} \\ \text{forgetting} \\ \text{factor} \end{array}$$

$$F(k+1) = \frac{1}{\lambda} \left[ F(k) - \frac{F(k)\phi(k)\phi(k)^T F(k)}{\lambda + \phi(k)^T F(k)\phi(k)} \right]$$

$$F^{-1}(k+1) = \lambda F^{-1}(k) + \phi(k)\phi^T(k)$$

# RLS with forgetting factor

**A-posteriori version (used to prove that  $e(k) \rightarrow 0$ ):**

$$e^o(k+1) = y(k+1) - \phi^T(k)\hat{\theta}(k)$$

$$e(k+1) = \frac{\lambda e^o(k+1)}{\lambda + \phi^T(k)F(k)\phi(k)}$$

$$\hat{\theta}(k+1) = \hat{\theta}(k) + \frac{1}{\lambda}F(k)\phi(k)e(k+1)$$

$$F(k+1) = \frac{1}{\lambda} \left[ F(k) - \frac{F(k)\phi(k)\phi(k)^T F(k)}{\lambda + \phi(k)^T F(k)\phi(k)} \right]$$

# RLS with forgetting factor

The gain of the RLS with FF may blow up

$$\text{tr} [F(k)] = \frac{1}{\lambda} \text{tr} [F(k-1)] - \frac{\|F(k-1)\phi(k-1)\|^2}{\lambda^2 + \lambda\phi^T(k-1)F(k-1)\phi(k-1)}$$

if  $\phi(k)$  is not persistently exciting  
(more on this later)

# General PAA gain formula

$$F^{-1}(k+1) = \lambda_1(k) F^{-1}(k) + \lambda_2(k) \phi(k) \phi^T(k)$$

$$0 < \lambda_1(k) \leq 1$$

$$0 \leq \lambda_2(k) < 2$$

- **Constant adaptation gain:**  $\lambda_1(k) = 1, \lambda_2(k) = 0$   
*(We talked about this case in the previous lecture)*
- **RLS:**  $\lambda_1(k) = 1, \lambda_2(k) = 1$
- **RLS with forgetting factor:**  $\lambda_1(k) < 1, \lambda_2(k) = 1$

# General PAA gain formula

$$F^{-1}(k+1) = \lambda_1(k) F^{-1}(k) + \lambda_2(k) \phi(k) \phi^T(k)$$

$$0 < \lambda_1(k) \leq 1$$

$$0 \leq \lambda_2(k) < 2$$

$$F(k+1) = \frac{1}{\lambda_1(k)} \left[ F(k) - \lambda_2(k) \frac{F(k) \phi(k) \phi^T(k) F(k)}{\lambda_1(k) + \lambda_2(k) \phi^T(k) F(k) \phi(k)} \right]$$

$$F(0) = F^T(0) > 0$$

# General PAA

**A-priori version:**

$$e^o(k+1) = y(k+1) - \phi^T(k)\hat{\theta}(k)$$

$$\hat{\theta}(k+1) = \hat{\theta}(k) + \frac{1}{\lambda_1(k) + \phi^T(k)F(k)\phi(k)} F(k)\phi(k)e^o(k+1)$$

$$F(k+1) = \frac{1}{\lambda_1(k)} \left[ F(k) - \lambda_2(k) \frac{F(k)\phi(k)\phi^T(k)F(k)}{\lambda_1(k) + \lambda_2(k)\phi^T(k)F(k)\phi(k)} \right]$$

When  $\lambda_2(k) = 1$ , the parameter estimate equation simplifies to

$$\hat{\theta}(k+1) = \hat{\theta}(k) + F(k+1)\phi(k)e^o(k+1)$$



# General PAA

**A-posteriori version (used to prove that  $e(k) \rightarrow 0$ ):**

$$e^o(k+1) = y(k+1) - \phi^T(k)\hat{\theta}(k)$$

$$e(k+1) = \frac{\lambda_1(k)}{\lambda_1(k) + \phi^T(k)F(k)\phi(k)} e^o(k+1)$$

$$\hat{\theta}(k+1) = \hat{\theta}(k) + \frac{1}{\lambda_1(k)} F(k)\phi(k)e(k+1)$$

$$F(k+1) = \frac{1}{\lambda_1(k)} \left[ F(k) - \lambda_2(k) \frac{F(k)\phi(k)\phi^T(k)F(k)}{\lambda_1(k) + \lambda_2(k)\phi^T(k)F(k)\phi(k)} \right]$$

# Additional Material

(you are not responsible for this)

- The Matrix Inversion Lemma
- Relationships for the General PAA

*(these will be included in the next version...)*

# Matrix Inversion Lemma (simplified version)

- Since  $\det(I + RL) = \det(I + LR)$  , we know that

$I + RL$  is invertible



$I + LR$  is invertible

- The matrix inversion lemma (simplified version) states that

$$(I + RL)^{-1} = I - R(I + LR)^{-1}L$$

# Matrix Inversion Lemma (simplified version)

$$(I + RL)^{-1} = I - R(I + LR)^{-1}L$$

**Proof:**

Define  $\Phi = I - R(I + LR)^{-1}L$

We want to show that  $(I + RL)\Phi = I$

$$(I + RL)\Phi = (I + RL) - \underbrace{(I + RL)R(I + LR)^{-1}L}_{R + RLR = R(I + LR)}$$

$$\begin{aligned} (I + RL)\Phi &= I + RL - R(I + LR)(I + LR)^{-1}L \\ &= I + RL - RL \end{aligned}$$



# Matrix Inversion Lemma

If  $A$ ,  $C$ , and  $(A+UCV)$  are invertible, then

$$(A+UCV)^{-1} = A^{-1} - A^{-1}U (C^{-1} + VA^{-1}U)^{-1} VA^{-1}$$

**Proof:**

$$\begin{aligned} (A + UCV)^{-1} &= \left[ (I + UCV A^{-1}) A \right]^{-1} \\ &= A^{-1} (I + UCV A^{-1})^{-1} \\ &= A^{-1} \left[ I - UC (I + VA^{-1}UC)^{-1} VA^{-1} \right] \\ &= A^{-1} \left[ I - U \left[ (I + VA^{-1}UC) C^{-1} \right]^{-1} VA^{-1} \right] \\ &= A^{-1} - A^{-1}U (C^{-1} + VA^{-1}U)^{-1} VA^{-1} \end{aligned}$$



# Relationships for General PAA

$$F(k+1) = \frac{1}{\lambda_1(k)} \left[ F(k) - \lambda_2(k) \frac{F(k)\phi(k)\phi^T(k)F(k)}{\lambda_1(k) + \lambda_2(k)\phi^T(k)F(k)\phi(k)} \right]$$

**Proof:** We know that

$$F^{-1}(k+1) = \lambda_1(k)F^{-1}(k) + [\lambda_2(k)\phi(k)]\phi^T(k)$$

By the Matrix Inversion Lemma

$$F(k+1) = \frac{1}{\lambda_1(k)}F(k) - \left[ \frac{1}{\lambda_1(k)}F(k) \right] [\lambda_2(k)\phi(k)] \left[ \frac{1}{1 + \phi^T(k) \left[ \frac{1}{\lambda_1(k)}F(k) \right] [\lambda_2(k)\phi(k)]} \right] \phi^T(k) \left[ \frac{1}{\lambda_1(k)}F(k) \right]$$

This simplifies to the stated expression for  $F(k+1)$



# Relationships for General PAA

$$F(k+1)\phi(k) = \frac{1}{\lambda_1(k) + \lambda_2(k)\phi^T(k)F(k)\phi(k)} F(k)\phi(k)$$

**Proof:**

$$F^{-1}(k+1) = \lambda_1(k)F^{-1}(k) + \lambda_2(k)\phi(k)\phi^T(k)$$

$$\Downarrow$$

$$\begin{aligned} F(k+1) [F^{-1}(k+1)] F(k)\phi(k) \\ = F(k+1) [\lambda_1(k)F^{-1}(k) + \lambda_2(k)\phi(k)\phi^T(k)] F(k)\phi(k) \end{aligned}$$

$$\Downarrow$$

$$\begin{aligned} F(k)\phi(k) &= \lambda_1(k)F(k+1)\phi(k) \\ &\quad + \lambda_2(k)F(k+1)\phi(k)\phi^T(k)F(k)\phi(k) \\ &= F(k+1)\phi(k) [\lambda_1(k) + \lambda_2(k)\phi^T(k)F(k)\phi(k)] \end{aligned}$$



# Relationships for General PAA

$$e(k+1) = \frac{\lambda_1(k)}{\lambda_1(k) + \phi^T(k)F(k)\phi(k)} e^o(k+1)$$

**Proof:**

$$\tilde{\theta}(k+1) = \tilde{\theta}(k) - \frac{1}{\lambda_1(k)} F(k)\phi(k)e(k+1)$$



$$\underbrace{\phi^T(k)\tilde{\theta}(k+1)}_{\substack{\uparrow \\ e(k+1)}} = \phi^T(k) \left[ \tilde{\theta}(k) - \frac{1}{\lambda_1(k)} F(k)\phi(k)e(k+1) \right]$$

$$= \underbrace{\phi^T(k)\tilde{\theta}(k)}_{e^o(k+1)} - \frac{1}{\lambda_1(k)} \phi^T(k)F(k)\phi(k)e(k+1)$$



# Relationships for General PAA

$$e(k+1) = \frac{\lambda_1(k)}{\lambda_1(k) + \phi^T(k)F(k)\phi(k)} e^o(k+1)$$

**Proof (continued):**

From the previous slide,

$$e(k+1) = e^o(k+1) - \frac{1}{\lambda_1(k)} \phi^T(k)F(k)\phi(k)e(k+1)$$



$$[\lambda_1(k) + \phi^T(k)F(k)\phi(k)] e(k+1) = \lambda_1(k)e^o(k+1)$$

